

### **Hyundai Rotem Company**

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Ref No.	RM\1A-05-06-15\D0003\R02	
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# Propulsion System Main Line Test Procedure for Propulsion System

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	Date	Name	Signature



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### **REVISION HISTORY**

Rev. Page Details			tails	Date	
No.	2 4.60	From	То	Date	
00	00 All First Issued				
	5	Add the test item 'System Isolation	Test' in table 1	Aug. 12. 2010	
- 1	7,8	Add the measuring signal for energy			
	8	Make sure that the coke of all braking pipes is in normal position.	Make sure that the cock of all braking pipes is in normal position.		
	9	1) After –, connect a wire to earth from the output terminal of VVVF inverter.	1) After ~, connect a wire to earth from the input terminal of VVVF inverter.		
1	10	Add the test procedure for system is	solation test	1	
01	12	Table 5 contents 'Min. Powering' and 'Min. Braking'	Table 5 contents 'Max. Powering' and 'Max. Braking'	Nov. 19. 2010	
	11	Table 7 subject for Re-Powering Test	Table 7 subject - for Slip/Slide Test		
	14	Table 11 subject  Dynamic Brake Performance Test	Table 11 subject Electric Brake Test		
	15	Add measuring position(inlet air ter			
	16	Add the test item 'System Isolation load condition	]		
	21	Add measuring position(inlet air ter result sheet for AW3 load condition	U		



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#### 1. General

This test procedure describes the test to confirm the function and performance of propulsion system in the main line.

#### 2. Applied Standard

IEC 61133: Electric traction-Rolling stock-Test methods for electric and thermal/electric rolling stock on completion of construction and before entry into service.

#### 3. Reference Document and Drawing

RM\1A-03-01-01\D0017(REDE105121) Configuration of Propulsion system

RM\1A-03-01-01\D0018(REDE105123) Train Performance

RM\1A-03-01-01\D0019(REDE105145) Running Simulation

RM\1A-03-02-15\D0001(REDE106466) Technical Description of Propulsion System RM\1A-03-03-15\D0001(REDE108133) Technical Description of Propulsion System

REDE105633 Interface Specification between VVVF and BCU

RVS00001AB0 Diagram, Main, Circuit
RVS00004AB0 Low Voltage Diagram

#### 4. Test Item

Table 1 shows the detail test item, test type, test place, vehicle load condition and applied standard.



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Table 1. Test Items

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	T		Test type		Test	Load	Applied	
No		Test item			Routine test	Place	condition Note1)	Standard Clause
1		Input Signal Confirmation		•	•	Depot	AW0	IEC 61133 / 8.17
2			Start Sequence	•	•	Depot	AW0	IEC 61133 / 8.17
3	Traction System Test	Sequence	Stop Sequence	•	•	Depot	AW0	IEC 61133 / 8.17
4		Test	Grounding Protection Test	•	-	Depot	AW0	IEC 61133 / 8.17
5			System Isolation Test	•	-	Depot	AW0	IEC 61133 / 8.17
6		Tractive Effort Test	Powering Test	•	•	Main Line	AW0/ AW3	IEC 61133 / 9.2
7			Re-powering Test	•	-	Main Line	AW0/ AW3	IEC 61133 / 9.2
8			Powering Test in minimum voltage condition	•	-	Main Line	AW0/ AW3	IEC 61133 / 9.2
9	Traction Performance		Acceleration/Jerk Test	•	•	Main Line	AW0/ AW3	IEC 61133 / 9.2
10	Test		Slip/Slide Test	•	-	Main Line	AW0/ AW3	IEC 61133 / 9.2
11			Rescue Performance Test	•	-	Main Line	AW0+AW3	IEC 61133 / 9.2
12		Speed Characteri stics Test	Maximum Speed Test	•	-	Main Line	AW0/ AW3	IEC 61133 / 9.2
13			y Time/Energy tion Measurement	•	-	Main Line	AW3	IEC 61133 / 9.3
14	Electric Brake Test		•	-	Main Line	AW0/ AW3	iEC 61133 / 9.4.1.8	
15	Traction Thermal Capacity Test			•	-	Main Line	AW3	IEC 61133 / 9.5

Note1) Load condition is applied in type test only and the routine test carry out in AW0 load condition.



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#### 5. Test Condition

- 1) Tests are carried out with a vehicle (2-car).
- 2) Tests should take place at the location of a level track.
- 3) Line voltage can be fed to a vehicle.
- 4) Tests are carried out under AW0 and AW3 conditions.

#### 6. Test Equipment

- 1) Data Chart recorder\*
- 2) Test Board and cable\*
- 3) Test Box\*
- 4) Multi Tester
- 5) Thermal Recorder\*
- 6) Thermometer
- 7) PTU(Portable Test Unit) for VVVF Inverter
- \* Equipments are needed in type test only

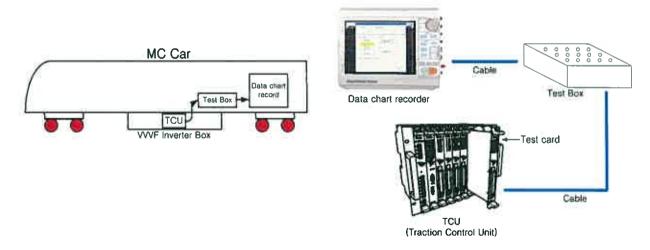


Fig.1 Measurement Diagram



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### 7. Measuring Signal Description

Table 2. Measuring Signal

No.	Channel No.	Signal	Signal Description	Applied Test
1	Ch. 1	V_LINE	Over Head Wire Voltage[V]	
2	Ch. 2	V_FC	Filter Capacitor Voltage[V]	1
3 Ch. 3 I_LINE 4 Ch. 4 PMF		I_LINE	Input Current[A]	
		PMF	Modulation Rate[%]	1
5	Ch. 5	I_MOTOR	Motor Current[A]	1
6	Ch. 6	PWM	PWM Command[%]	
7	Ch. 7	Tq_ref	Torque Reference[Nm]	Traction Performance
8	Ch. 8	Tq_real	Real Torque[Nm]	Test
9	Ch. 9	Flux	Flux[Wb]	
10	Ch. 10	I_BCH	Brake Chopper Current[A]	
11	Ch. 11	SPEED	Vehicle Velocity[km/h]	
12	Ch. 12	α, β	Acceleration and Deceleration[m/s <sup>2</sup> ]	
13	Ch. 13	EB	Emergency Brake Command (High : on, Low : off)	
14	Ch. 1	V_LINE1	Over Head Wire Voltage of TCU1[V]	
15	Ch. 2	V_FC1	Filter Capacitor Voltage of TCU1 [V]	
16	Ch. 3	I_LINE1	Input Current of TCU1 [A]	
17 Ch. 4 V_LINE2		V_LINE2	Over Head Wire Voltage of TCU2 [V]	
18	Ch. 5	V_FC2	Filter Capacitor Voltage of TCU2 [V]	Traction
19	Ch. 6	I_LINE2	Input Current of TCU2 [A]	Performance Test
20	Ch. 7	M_con1	Powering energy consumption for TCU1[kWh]	(Energy
21	Ch. 8	B_con1	Braking energy consumption for TCU1[kWh]	consumption)
22	Ch. 9	M_con2	Powering energy consumption for TCU2[kWh]	
23	Ch. 10	B_con2	Braking energy consumption for TCU2[kWh]	
24	Ch. 11	SPEED	Vehicle Velocity[km/h]	
25 Ch. 12 PWM		PWM	PWM Command[%]	
26	Ch. 1	Th_atm	Atmosphere Temperature	Traction
27 Ch. 2 Th_TMF		Th_TMF	Frame temperature of traction motor	thermal capacity test



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No.	Channel No.	Signal	Signal Description	Applied Test
28	Ch. 3	Th_TMBDE	Bearing Cap DE temperature of traction motor	
29	Ch. 4	Th_TMBODE	Between speed sensor housing and Frame ODE temperature of traction motor	
30	Ch. 5	Th_TMout	Outlet air temperature of traction motor	
31	Ch. 6	Th_TMin	Inlet air temperature of traction motor	
32	Ch. 7	Th_FL	Coil temperature of filter reactor	
33	Ch. 8	Th_Stack	IGBT stack temperature of VVVF inverter	
34	Ch. 9	Th_Cap	Capacitor temperature of VVVF inverter	
35	-	Th_axle boxes	Axle box temperature	

#### 8. Preparation for Test

- 1) Make sure that the cock of all braking pipes is in normal position.
- 2) Make sure that all the equipment and switches in cabin and distribution panel are in normal position.
- 3) Check air pipes and jumper couplers.
- 4) Check the wiring and the box of high tension on cars.

#### 9. Test Procedure

#### 9.1 Traction System Test

Objective: to verify that traction system responds correctly to its control signals in order to demonstrate its fitness for dynamic test.

#### 9.1.1 Input Signal Confirmation

- 1) Turn the CCOS switch to 'TEST' mode in VVVF inverter.
- 2) Turn on the control voltage of vehicle.
- 3) Set the reverse handle to forward/reverse position and set the power/brake handle to power/brake position in driver cabin of Tc car and Mc car
- 4) According to position of master controller, confirm 'F', 'R', 'P',' B' LED lighting in DIN board of VVVF Inverter control unit.
  - In case of operation in Tc car cabin, the forward/reverse signal is indicated to the contrary.
- 5) Push the 'Boost', 'System Isolation', 'HB reset' and 'EB(Emergency Brake)' button in driver cabin of Tc car and Mc car



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6) According to buttons operation, confirm 'Boost', 'HBreset', 'SYSiso' and EB LED lighting in DIN board of VVVF inverter control unit.

In case of 'EB' signal, normally EB LED turns on and if applying the emergency brake, EB LED on control unit turns off.

#### 9.1.2 Sequence Test

Check the start sequence, stop sequence for propulsion system in high voltage condition and check the fault sequence for it in low voltage condition.

- Start sequence test
  - 1) Turn the CCOS switch to 'NORMAL' mode in VVVF inverter.
  - 2) Turn on the control voltage of vehicle.
  - 3) Push the pantograph raise button for energizing the high voltage to vehicle.
  - 4) Confirm the high voltage value by using DU(Display Unit) of TMS(Train Monitoring System)
  - 5) Set the reverse handle to 'Forward' position and set the power/brake handle to 'Brake' position in driver cabin of Tc car and Mc car
  - Confirm the starting sequence of contactors in line breaker box by using PTU(Portable Test Unit).
  - 7) Operation order: HSCB close → CHK1,2 close → LB1,2 close → CHK1,2 open

#### - Stop sequence test

- 1) After propulsion system complete to operate the start sequence, set the reverse handle to 'Off' position
- 2) Confirm the stop sequence of contactors in line breaker box by using PTU.
- 3) Operation order: LB1,2 open → HSCB open
- 4) Also after propulsion system complete to operate the start sequence, push the pantograph down button
- 5) And then confirm the stop sequence of contactors in line breaker box by using PTU.

#### - Grounding protection test

- 1) After the operation of propulsion system is shut down, connect a wire to earth from the input terminal of VVVF inverter.
- 2) Turn on the control voltage of vehicle.
- 3) Push the pantograph raise button for energizing the high voltage to vehicle.



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- 4) Set the reverse handle to 'Forward' position and set the power/brake handle to 'Power' position in driver cabin.
- 5) Confirm that propulsion system detects the fault for grounding and LB open.
- System Isolation test
  - 1) When the propulsion system starts the operation and the vehicle is moving, push "SYSTEM ISOLATION" button on operation panel of drive cab.
  - 2) Confirm that the propulsion system stops the operation and HSCB and LB open.
  - Confirm that the operation of propulsion system is restarted by pushing 'HSCB RESET' button.

#### 9.2 Traction Performance Test

Objective: to verify that the traction performance meets the specified criteria.

#### Preparation of performance test

- 1) Turn the CCOS switch to 'NORMAL' mode in VVVF inverter.
- 2) Turn on the control voltage of vehicle.
- 3) Push the pantograph raise button for energizing the high voltage to vehicle.
- 4) Confirm the inputted high voltage

#### 9.2.1 Powering Test

- 1) Operate the vehicle according to Table 3 running procedure
- 2) Confirm that propulsion system is operated without abnormal motor current and any protection detection.

Table 3. Running Procedure for Powering Test

No.	Running Procedure	Remark
1	Min. Powering → Vehicle speed 20 km/h → coasting → Min. Braking	
2	Max. Powering → Vehicle speed 40 km/h → coasting → Max. Braking	
3	Max. Powering → Vehicle speed 60 km/h → coasting → Max. Braking	

#### 9.2.2 Re-Powering Test

- 1) Operate the vehicle according to Table 4 running procedure
- 2) Confirm that propulsion system is operated without abnormal motor current and any protection detection.



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#### Table 4.Running Procedure for Re-Powering Test

No.	Running Procedure	Remark
1	Min. Powering → Vehicle speed 10 km/h → coasting → Min. Powering → Vehicle speed 20 km/h → coasting → Max. Braking	
2	Max. Powering → Vehicle speed 40 km/h → coasting → Max. Powering → Vehicle speed 60 km/h → coasting → Max. Braking	

#### 9.2.3 Powering Test in Minimum Voltage Condition

- 1) Adjust OHW voltage as about DC 1,300V
- 2) Operate the vehicle according to Table 5 running procedure
- 3) Confirm that propulsion system is operated without abnormal motor current and any protection detection.
- 4) Confirm that maximum traction performance is maintained

#### Table 5. Running Procedure for Minimum Voltage Powering Test

No.	Running Procedure	Remark
1	Max. Powering → Vehicle speed 60 km/h → coasting → Max. Braking	

#### 9.2.4 Acceleration/Jerk Test

- 1) Operate the vehicle according to Table 6 running procedure
- Confirm that the measured acceleration rate and starting jerk meet the following specification.
- 3) The acceleration rate must be measured in on-level track and straight track condition.
  - \* Acceleration rate/Jerk rate criteria
  - Max. acceleration rate: less than 0.90m/s2
  - Average acceleration rate from 0 to 65 km/h: not less than 0.69m/s<sup>2</sup>
  - Average acceleration rate from 0 to 100 km/h: not less than 0.34m/s<sup>2</sup>
  - Jerk rate : less than 0.75m/s

#### Table 6.Running Procedure for Acceleration/Jerk Test

ì			
	No.	Running Procedure	Remark
	1	Max, Powering → Vehicle speed more than100 km/h → coasting → Max, Braking	



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#### 9.2.5 Slip/Slide Test

- 1) Operate the vehicle according to Table 7 running procedure
- 2) Test carry out in wet condition track.
- Confirm that the torque pattern can be controlled according to rail condition and can be accelerated / decelerated.

Table 7. Running Procedure for Slip/Slide Test

No.	No. Running Procedure	
1	Spray the water on track → Max. Powering → Vehicle speed 60 km/h → coasting → Max. Braking	Wet track condition

#### 9.2.6 Rescue Performance Test

- 1) Connect the rescued vehicle(AW3 load condition) up to rescuing vehicle(AW0)
- 2) The connected vehicle (AW0+AW3) stops in maximum gradient track of Wellington service track. And test is performed in dry track and wet track condition.
- 3) Operate the vehicle according to Table 8 running procedure with boost recovery button.
- 4) Confirm that the connected vehicle that stops in maximum gradient track should run correctly in maximum gradient track. And for wet condition, confirm that the connected vehicle passes correctly through the maximum gradient track.

Table 8.Rescue Performance Test

No.	Running Procedure	Remark
1	Push the boost recovery button → Max. Powering → Vehicle speed 20 km/h → coasting → Max. Braking	

#### 9.2.7 Maximum Speed Characteristic Test

- 1) Operate the vehicle according to Table 9 running procedure.
- 2) The test is carried out as following two soft ware versions of VVVF Inverter;
  - Software without over speed protection function for confirming the maximum speed(121km/h)
  - Software with over speed protection function for confirming the removing the traction power more than 115km/h
- 3) Confirm that VVVF inverter should operate correctly at the maximum speed.



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4) Confirm that at vehicle speeds in excess of 110km/h in performance characteristic the maximum powering tractive effort will be linearly decreased to zero as the unit speed approaches 115km/h.

Table 9.Maximum Speed Characteristic Test

No.	Running Procedure	Remark
1	Max. Powering → Vehicle speed more than 121 km/h → coasting → Max.  Braking	

#### 9.2.8 Journey Time / Energy Consumption Measurement

This test must be carried out after completing the traction performance test and brake system test for main line test.

 The vehicle in AW3 load condition moves in following service track as normal revenue schedule.

#### Test Route

- Wellington station to Paraparaumu station
- Paraparaumu station to Wellington station
- Wellington station to Upper Hutt station
- Upper Hutt station to Wellington station
- Wellington station to Johnsonville station
- Johnsonville station to Wellington station
- Measure the total journey time and energy consumption for each route.
- 3) In case of energy consumption, Measurement is applied in only traction power.
- 4) Confirm that the journey time and energy consumption meets the table 10 criteria. In case of Wellington station to Johnsonville station and Johnsonville station to Wellington station, the energy consumption is measured as reference data.
- 5) This test shall be performed on vehicles which have completed the agreed period of running-in and in accordance with the following conditions
  - load conditions : AW3 load
  - Track condition : dry and wet condition
  - calm weather
  - temperature range : -25°C ~ 40°C



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Table 10.Criteria for journey time and energy consumption

Route	Journey Time [hh:mm:ss]	Energy Consumption [kWh]	Remark
Wellington station to Paraparaumu station	00:54:08	Less than 237.0	
Paraparaumu station to Wellington station	00:54:08	Less than 195.0	
Wellington station to Upper Hutt station	00:44:54	Less than 174.2	
Upper Hutt station to Wellington station	00:44:27	Less than 135.7	
Wellington station to Johnsonville station	00:21:02	-	
Johnsonville station to Wellington station	00:21:07	-	

#### 9.3 Electric Brake Test

- 1) Operate the vehicle according to Table 11 running procedure
- 2) Confirm the following performance;
  - The unit will maximise the use of regenerative braking and then rheostatic braking before using friction braking
  - Electric braking will be provided as part of the normal service brake. The electric braking will comprise regenerative and rheostatic braking.
  - On dry track the electric braking on the motor car must be maximised.
  - For electric braking, regenerative braking will be maximised, subject to overhead receptivity.
  - Rheostatic braking will be continuously rated for all braking duty cycle and can be used for the discharge of power from the traction circuit.
  - The current of traction motor does not exceed the design value.
  - There is no abnormal self-excitation of the traction motor.
  - In the case of regenerative braking and in the event of loss of the power supply, external short circuit of the power supply, pantograph bounce, lack of receptivity of the power supply, line gap or neutral sections, transition takes place to friction brake.
  - The electric braking builds up and releases steadily without significant jerk.

Table 11. Test Electric Brake Test

No.	Running Procedure	Remark
1	Max. Powering → Vehicle speed more than 100 km/h → coasting → Max.	
'	Braking	



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#### 9.4 Traction Thermal Capacity Test

Objective : to verify that the traction equipment can operate the specified duty cycle within specified temperature limits.

This test must be carried out after completing the traction performance test and brake system test for main line test and will be tested with journey time / energy consumption measurement at the same time.

1) The vehicle in AW3 load condition moves in following service track as normal revenue schedule.

**Test Route** 

- One round trip between Wellington station and Paraparaumu station
- One round trip between Wellington station and Upper Hutt station
- 2) Measure the temperature of each equipment part which is indicated in table 12 during one round trip for test route
- 3) In case of temperature of axle box in bogie, measure the initial temperature before starting and then measure the risen temperature of it after finishing the one round trip
- 4) Confirm that the risen temperature after one round trip meets the criteria of table 12.

Table 12. Measuring Position and Criteria for Thermal Capacity Test

No	Measuring Position	Criteria for Temperature Rising	Remark
1	Atmosphere Temperature	-	
2	Frame temperature of traction motor	Less than 200 °C	
3	Bearing Cap DE temperature of traction motor	Less than 115 °C	
4	Between speed sensor housing and Frame ODE temperature of traction motor	Less than 115 °C	
5	Outlet air temperature of traction motor	-	
6	Inlet air temperature of traction motor	-	
7	Coil temperature of filter reactor	Less than 155 °C	
8 IGBT stack temperature of VVVF inverter		Less than 100 ℃	
9 Capacitor temperature of VVVF inverter		Less than 70 °C	
10	Axie box temperature	Less than 80 °C	



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#### 10. Test Result Sheet

#### 10.1 Test Result Sheet for AW0 load condition

PROJECT	Matangi	GWRL	Approval		
MANUFACTURE	Hyundai Rotem	GVAKE			
ITEM	Propulsion system test in main line HYUNDAI		Inspector	Confirmer	
Vehicle NO.		ROTEM			
DATE	2010	RESULT	PASS / FAIL		

#### **Traction System Test**

No.	Test Item		Criteria	Result / Mea	suring value
	1	_	(=1.0.0	TCU1	TCU2
		F	'F' led on	Pass / Fail	Pass / Fail
		R	'R' led on	Pass / Fail	Pass / Fail
		Р	'P' led on	Pass / Fail	Pass / Fail
1	Input Signal	В	'B' led on	Pass / Fail	Pass / Fail
•	Confirmation	Boost	'Boost' led on	Pass / Fail	Pass / Fail
		System Isolation	'SYSiso' led on	Pass / Fail	Pass / Fail
		HB Reset	'HBres' led on	Pass / Fail	Pass / Fail
		EB	'EB' led off	Pass / Fail	Pass / Fail
û	Sequence Test	Start Sequence	HB close →CHK1,2 close →LB close1,2 →CHK1,2 open	Pass / Fail	Pass / Fail
		Stop Sequence	LB1,2 off → HB off	Pass / Fail	Pass / Fail
2		Grounding Protection	Detect the fault and LB1 open	Pass / Fail	
		System Isolation Test	The operation of propulsion system is stop (HB, LB open) The operation of propulsion system is restarted by 'HB RESET' button	Pass / Fail	Pass / Fail



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#### **Traction Performance Test**

No.	Test Item		Criteria	Result / Meas	suring value
-			Operated without abnormal	МС	TC
1		Powering Test	motor current and any protection detection	Pass / Fail	Pass / Fail
2		Re-Powering Test	Operated without abnormal motor current and any protection detection	Pass / Fail	Pass / Fail
3		Powering Test in Minimum Voltage	Maximum Traction performance is maintained	Pass / Fail	Pass / Fail
			Max. Acceleration rate	Pass / Fail	Pass / Fail
			- Less than 0.9 m/s <sup>2</sup>	m/s²	m/s <sup>2</sup>
			Acceleration rate - Not less than 0.69 m/s <sup>2</sup> 0 to 65 km/h	Pass / Fail	Pass / Fail
141		Accelerstion /Jerk Test		m/s²	m/s²
4	Tractive Effort		Acceleration rate - Not less than 0.34 m/s <sup>2</sup> 0 to 100 km/h	Pass / Fail	Pass / Fail
	Test			m/s²	m/s²
			Jerk Rate	Pass / Fail	Pass / Fail
			- less than 0.75m/s <sup>3</sup>	m/s³	m/s³
5		Slip/Slide Test	Torque pattern can be controlled according to rail condition	Pass / Fail	Pass / Fail
6		Rescue Performance Test	The connected vehicle should run in gradient track	Pass	/ Fail
7		Maximum Speed Characteristic Test	VVVF Inverter should operate correctly at the maximum speed	Pass	/ Fail
ñ			Conform the over speed protection	Pass	/ Fail

#### **Electric Brake Test**

#### Pass / Fail

No.	Conformation Item	Result
1	The unit will maximise the use of regenerative braking and then rheostatic braking before using friction braking	Pass / Fail
2	Electric braking will be provided as part of the normal service brake. The electric braking will comprise regenerative and rheostatic braking.	Pass / Fail
3	On dry track the electric braking on the motor car must be maximised.	Pass / Fail



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No.	Conformation Item	Result
4	For electric braking, regenerative braking will be maximised, subject to overhead receptivity.	Pass / Fail
5	Rheostatic braking will be continuously rated for all braking duty cycle and can be used for the discharge of power from the traction circuit.	Pass / Fail
6	The current of traction motor does not exceed the design value.	Pass / Fail
7	There is no abnormal self-excitation of the traction motor.	Pass / Fail
8	In the case of regenerative braking and in the event of loss of the power supply, external short circuit of the power supply, pantograph bounce, lack of receptivity of the power supply, line gap or neutral sections, transition takes place to friction brake.	Pass / Fail
9	The electric braking builds up and releases steadily without significant jerk.	Pass / Fail



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### 10.2 Test Result Sheet for AW3 load condition

PROJECT	Matangi	GWRL	Approval	
MANUFACTURE	Hyundai Rotem	GWKL		
ITEM	Propulsion system test in main line	HYUNDAI	Inspector	Confirmer
Vehicle NO.		ROTEM		
DATE	2010	RESULT	PASS / FAIL	

#### **Traction Performance Test**

No.	Test Item		Criteria	Result / Meas	suring value
			Operated without abnormal	МС	TC
1		Powering Test	motor current and any protection detection	Pass / Fail	Pass / Fail
2		Re-Powering Test	Operated without abnormal motor current and any protection detection	Pass / Fail	Pass / Fail
3		Powering Test in Minimum Voltage	Maximum Traction performance is maintained	Pass / Fail	Pass / Fail
	]		Max. Acceleration rate - Less than 0.9 m/s <sup>2</sup>	Pass / Fail	Pass / Fail
		Fractive Effort Test Acceleration Acceleration Jerk Test Acceleration Acceleration Acceleration Acceleration Acceleration Acceleration Acceleration Acceleration Acceleration		m/s²	m/s²
			Acceleration rate - Not less than 0.69 m/s <sup>2</sup> 0 to 65 km/h	Pass / Fail	Pass / Fail
4				m/s <sup>2</sup>	m/s²
4	Test		Acceleration rate - Not less than 0.34 m/s <sup>2</sup>	Pass / Fail	Pass / Fail
			0 to 100 km/h	m/s <sup>2</sup>	m/s <sup>2</sup>
			Jerk Rate - less than 0.75m/s³	Pass / Fail	Pass / Fail
				m/s³	m/s³
5	1	Slip/Slide Test	Torque pattern can be controlled according to rail condition	Pass / Fail	Pass / Fail
6		Maximum Speed Characteristic	VVVF Inverter should operate correctly at the maximum speed	Pass	/ Fail
		Test	Conform the over speed protection	Pass	/ Fail



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No.	Те	est Item	Criteria		Result / Measuring value	
		Journey Time	W to P	00:54:08	Pass / Fail	
			P to W	00:54:08	Pass / Fail	
			W to U	00:44:54	Pass / Fail	
	Journey Time / Energy	Measurement	U to W	00:44:27	Pass / Fail	
7	Consum ption Measure		W to J	00:21:02	Pass / Fail	
,	ment in dry		J to W	00:21:07	Pass / Fail	
	track conditio n		W to P	Less than 237kWh	Pass / Fail	
		Energy	P to W	Less than 195kWh	Pass / Fail	
		Consumption Measurement	W to U	Less than 174kWh	Pass / Fail	
			U to W	Less than 135kWh	Pass / Fail	
		ption	W to P	00:54:08	Pass / Fail	
			P to W	00:54:08	Pass / Fail	
			W to U	00:44:54	Pass / Fail	
	Time /		U to W	00:44:27	Pass / Fail	
8	Consum		W to J	00:21:02	Pass / Fail	
ľ	ment in wet	3	J to W	00:21:07	Pass / Fail	
	track conditio		W to P	Less than 237kWh	Pass / Fail	
16			P to W	Less than 195kWh	Pass / Fail	
			W to U	Less than 174kWh	Pass / Fail	
			U to W	Less than 135kWh	Pass / Fail	



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#### **Electric Brake Test**

Pass / Fail

No.	Conformation Item	Result
1	The unit will maximise the use of regenerative braking and then rheostatic braking before using friction braking	Pass / Fail
2	Electric braking will be provided as part of the normal service brake. The electric braking will comprise regenerative and rheostatic braking.	Pass / Fail
3	On dry track the electric braking on the motor car must be maximised.	Pass / Fail
4	For electric braking, regenerative braking will be maximised, subject to overhead receptivity.	Pass / Fail
5	Rheostatic braking will be continuously rated for all braking duty cycle and can be used for the discharge of power from the traction circuit.	Pass / Fail
6	The current of traction motor does not exceed the design value.	Pass / Fail
7	There is no abnormal self-excitation of the traction motor.	Pass / Fail
8	In the case of regenerative braking and in the event of loss of the power supply, external short circuit of the power supply, pantograph bounce, lack of receptivity of the power supply, line gap or neutral sections, transition takes place to friction brake.	Pass / Fail
9	The electric braking builds up and releases steadily without significant jerk.	Pass / Fail

#### **Traction Thermal Capacity Test**

Pass / Fail

Na	Measuring Position	Cuitouia	Result / Measuring value		
No.		Criteria	Start Temp.	End Temp.	
1	Atmosphere Temperature		°C	°c	
2	Frame temperature of traction motor	Less than 200 ℃	°c	ိင	
3	Bearing Cap DE temperature of traction motor	Less than 115 ℃	°C	°C	
4	Between speed sensor housing and Frame ODE temperature of traction motor	Less than 115 ℃	°C	°C	
5	Outlet air temperature of traction motor	•	°C	<b>°</b> C	
6	Inlet air temperature of traction motor	-	°C	°C	
7	Coil temperature of filter reactor	Less than 155 °C	*C _	°C	



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No.	Measuring Position	Criteria	Result / Measuring value	
			Start Temp.	End Temp.
8	IGBT stack temperature of VVVF inverter	Less than 100 ℃	°C	°C
9	Capacitor temperature of VVVF inverter	Less than 70 ℃	°C	ិ
10	Axle box temperature	Less than 80 ℃	°C	°C